



Demonstrating Autonomous Control, Remote Operation, and Human Factors for Microreactors Under Prototypic Conditions in PUR-1

NEUP Project 22-26910

2023 Microreactor Program Review

Stylianos Chatzidakis

Assistant Professor
School of Nuclear Engineering
Purdue University

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Goals & Objectives

Goal: Experimentally validate autonomous control and demonstrate its use by remotely operating and controlling PUR-1.

Objectives:

- Develop a modular autonomous control platform with various levels of automation using a remote workstation with AI/ML algorithms
- 2. Train AI/ML using physics-based microreactor models and realtime digital operation data collected from PUR-1
- 3. Perform testing and evaluate performance





Team Info

Purdue

- Stylianos Chatzidakis (Assistant Professor and Associate Reactor Director, SRO)
- True Miller (Reactor supervisor, SRO)
- Brian Jowers (Electronics/I&C reactor staff, RO)
- Konstantinos Vasili (Grad student AI/ML)

UNM

- Mohamed El-Genk (Professor)
- Timothy Schriener (Research Assistant Professor)

Collaborators

- Robert Ammon (Curtiss-Wright)
- Rick Vilim (ANL)

TPOC

Ben Baker (INL)





PUR-1 Fully Digital I&C







Before and after...



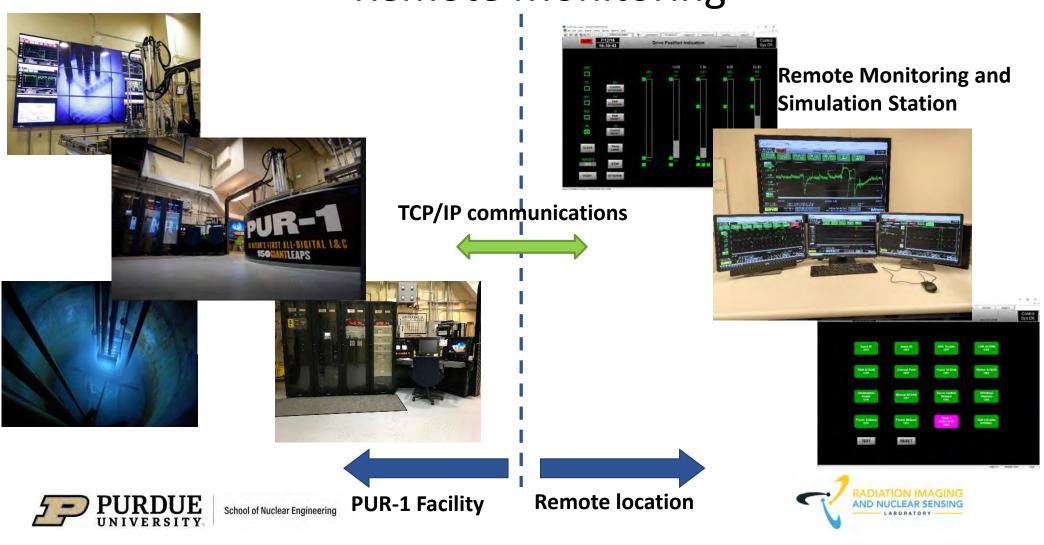
2019 - present

1960 - 2017

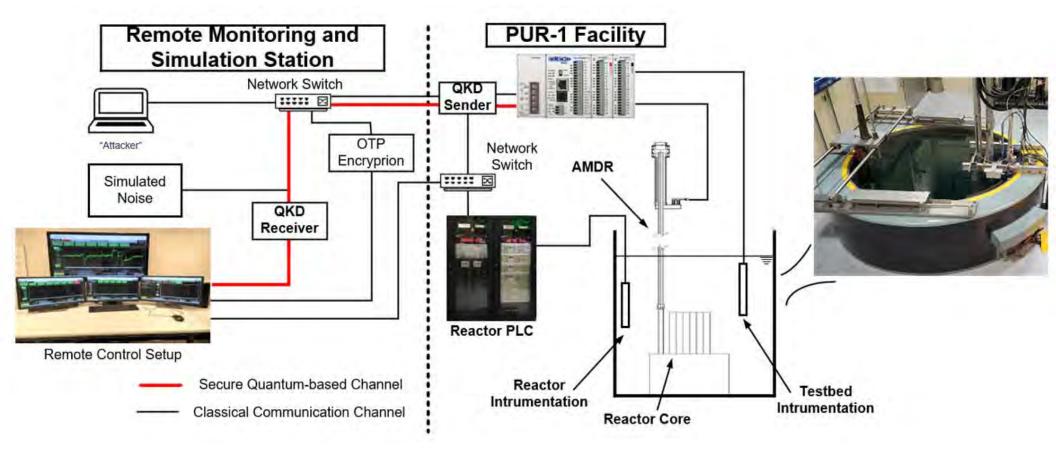




Remote Monitoring



Digital Twin Testbed





Instrumentation & Control

Instrumentation

- 4 neutron detectors (FC, UIC, CIC) => cps, % power, change rate
- 3 radiation area monitors (mR/hr)
- 1 air monitor (Ci/m3)
- Water chemistry (oC, μS/cm), confinement pressure (kPa)

Control

- RTP 3000, Ethernet-TCP/IP communications
- R-Time (sampling rate up to 1 kHz)

Archived data (process, network, and host)

- All instruments, operator actions, alarms, shim and reg rod positions, source position, HVAC, magnet, pump current/voltage, etc.
- PLC, UPS (battery status, freq, V, A), and system diagnostics
- Network traffic (bandwidth, packet analysis, etc.)
- Engineering workstation host system processes





Normal and Abnormal States

Normal operation/state

- Startup procedure
- Any power level up to 100% (up to 2% change rate per supervisor guidance)
- Irradiations
- Shutdown by gang lower or SCRAM
- Multiple operators
- Simulated abnormal states (tentative)
 - Power excursion (ramp up > 2%, alarm @6%), modify critical rod positions, etc.
 - Oscillations (e.g., equipment degradation), unusual power levels
 - Equipment on/off (pump, HVAC, temperature increase)
 - Cyber
 - Eavesdropping (e.g., process and operation data)
 - Data exfiltration (e.g., Monju type attack, steal host system data)
 - DoS (e.g., Davis-Besse, Browns-Ferry)
 - False data injection (e.g., Stuxnet type replay attack, data tampering)
 - Multiple scenarios (e.g., DoS for distraction+replay attack+oscillations)



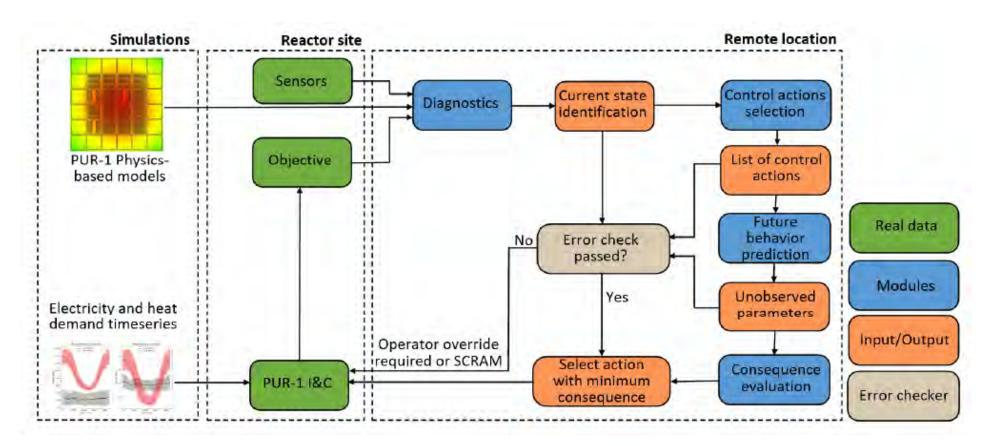
Project Schedule & Tasks

Task	Year											
	1st				2nd				3rd			
	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4
Architecture Development and 1 Training of ML/DL Algorithms												
1.1 Architecture Development												
1.2 Training of ML/DL Algorithms												
Testing and Demonstration on 2 PUR-1												
Testing and Demonstration on PUR-1												
Performance Evaluation and 3 Licensing Gap Analysis												
Performance Evaluation and 3.1 Vulnerability Assessment												
Microreactor Regulatory Licensing 3.2 Gap Analysis	3											





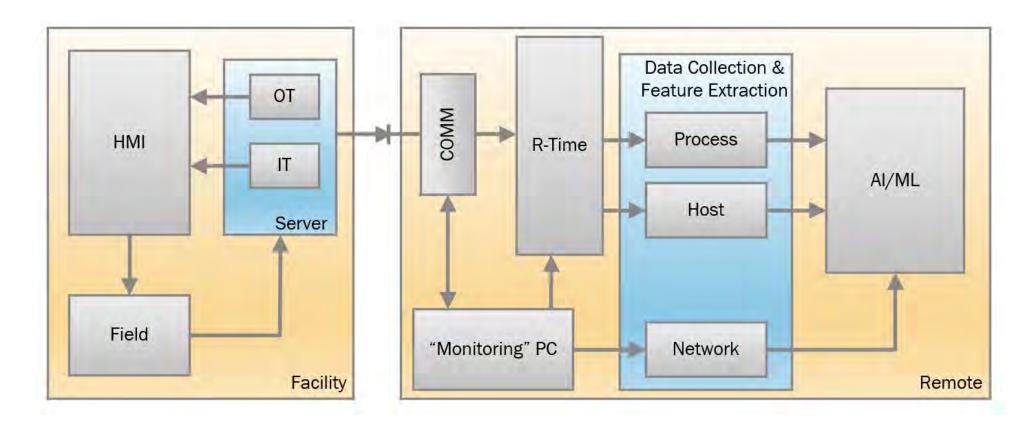
Early efforts...





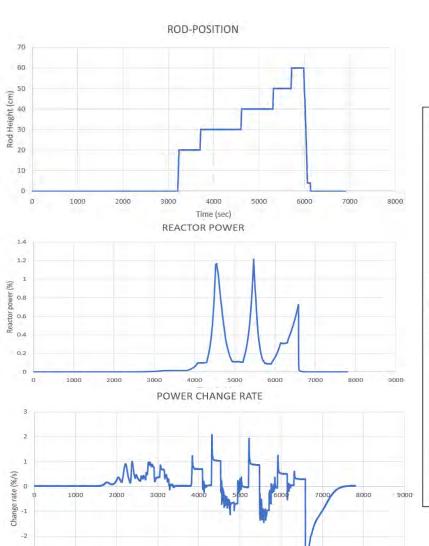


Early efforts...

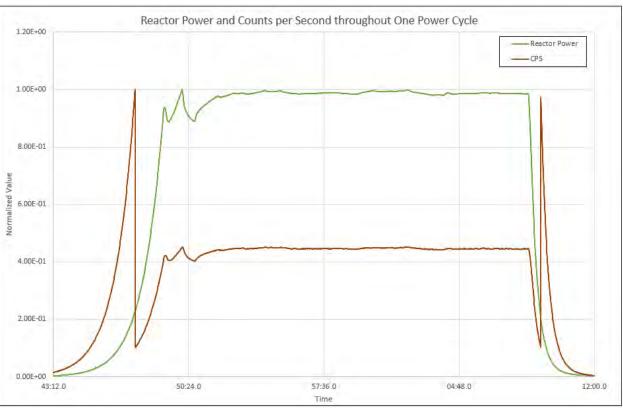








Time (sec)





Next steps

- Continue development of architecture
- Implement representative use case
 - Start-up
 - Power changes
- Develop microreactor model (VSLIMM)
- Generate data and train algorithms
- Test and optimize in PUR-1







Digital Twin Testbed Capabilities

Autonomous control using AI/ML

PUR-1 Facility

Control Workstation

Ethernet communications

Digital I&C

On-site data analytics

Cybersecurity: Delay transmission,

QKD Setup

Digital twin: OpenPLC, OpenMC, MCNP, COMSOL, RELAP5

Operation: steady state and transient operation



Denial-of-Service (DOS), False real data

transmission, Eavesdropping